

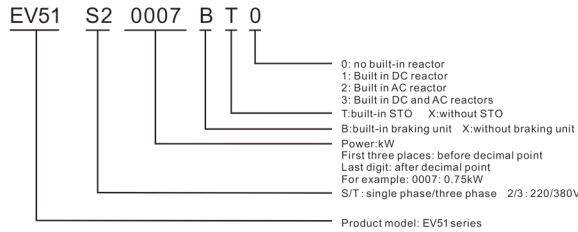


EV51 Series Inverter

--Special for carving machine

USER MANUAL

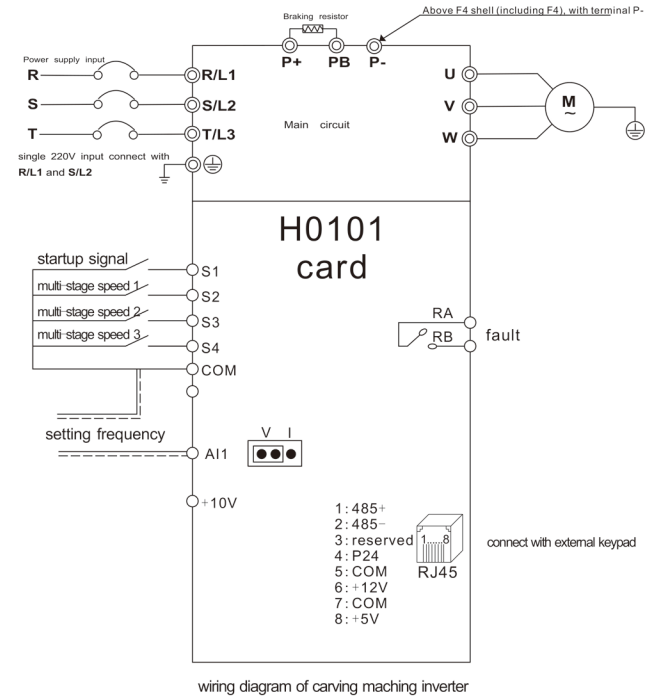
1.2 EV51 nameplate



1.3 EV51 series specifications and models

| Base.No | Models | Input voltage | input current (A) | Power (kW) | output current (A) | Adaptive motor (kW) |
|---------|---------------|---------------|-------------------|------------|--------------------|---------------------|
| F1 | EV51S20015BX0 | 1 phase 220V | 8.2 | 1.5 | 7.0 | 1.5 |
| | EV51S20022BX0 | 1 phase 220V | 14.0 | 2.2 | 12.5 | 2.2 |
| F2 | EV51T20037BX0 | 1 phase 220V | 23.0 | 3.7 | 15.2 | 3.7 |
| | | 3 phase 220V | 13.5 | | | |
| F3 | EV51T20055BX0 | 1 phase 220V | 38.6 | 5.5 | 23 | 5.5 |
| | | 3 phase 220V | 16.5 | | | |
| | EV51T20075BX0 | 3 phase 220V | 37 | 7.5 | 31 | 7.5 |
| F4 | EV51T20110BX0 | 3 phase 220V | 52 | 11 | 45 | 11 |
| | EV51T20150BX0 | 3 phase 220V | 68 | 15 | 58 | 15 |
| F1 | EV51T30015BX0 | 3 phase 380V | 5.8 | 1.5 | 3.7 | 1.5 |
| | EV51T30022BX0 | 3 phase 380V | 6.5 | 2.2 | 5.0 | 2.2 |
| | EV51T30030BX0 | 3 phase 380V | 12.6 | 3.0 | 7.0 | 3.0 |
| F2 | EV51T30040BX0 | 3 phase 380V | 14 | 4.0 | 10.5 | 4.0 |
| | EV51T30055BX0 | 3 phase 380V | 16 | 5.5 | 13 | 5.5 |
| F3 | EV51T30075BX0 | 3 phase 380V | 21 | 7.5 | 18 | 7.5 |
| | EV51T30110BX0 | 3 phase 380V | 28 | 11 | 24 | 11 |
| F4 | EV51T30150BX0 | 3 phase 380V | 36 | 15 | 30 | 15 |

NO.2 Wiring diagram for carving machine inverter



2. 1 Main circuit terminal description

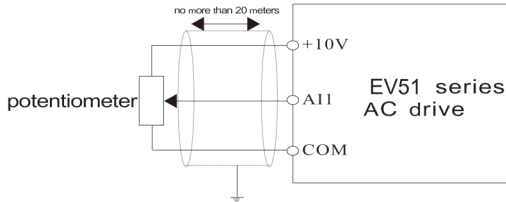
| Terminal identification | Name | Function description |
|-------------------------|-----------------------------------|--|
| | Grounding terminal | Safety grounding |
| R/L1、S/L2、T/L3 | Main circuit power input terminal | Connect three phase power supply, single phase power supply connect to R/L1, S/L2 |
| P+、PB | Braking terminal | Connect to external braking resistor |
| P+、P- | DC bus terminal | Two sets or more inverters use a common DC bus (Above F4 shell (including F4), with terminal P-) |
| U、V、W | output terminl | Connect to three phase motor |

2.2 Control terminal specification

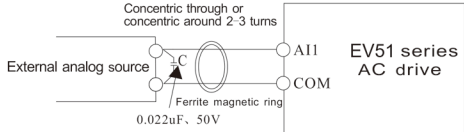
| Terminal identification | Name | Function description |
|-------------------------|------------------------|---|
| +10V | 10Vpower supply | Provide + 10V power supply to the outside, and the maximum output current is 50mA |
| AI1 | Analog input terminal | 1. input voltage rang: DC 0V~10V 2. Input current range: 0~20mA 3. Select voltage or current through SW1 jumper |
| COM | digit, analog ground | Isolate the internal from the communication ground GND |
| S1~S4 | Digital input terminal | 1. Optocoupler isolation 2. Input impedance: 2.4k Ω 3. Voltage range at level input: 9V~30V |
| RA RB | relay output | 1. Resistive load: 250VAC 3A/30VDC 3A 2. inductive load: 250VAC 0.2A/24VDC 0.1A(cos φ =0.4) |
| RJ45 | Network port | The keyboard can be led out or connected to the upper computer |

2. 3 Analog wiring

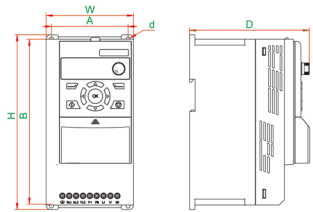
Because weak analog voltage signals are particularly vulnerable to external interference, shielded cables are generally required, and the wiring distance shall be as short as possible, not more than 20 meters. As shown below:



When some analog signals are seriously disturbed, filter capacitors or ferrite magnetic cores need to be added to the analog signal source side. As shown in the figure below:



NO.3 Product Dimension



| Framework | EV51 Series | | | | | |
|-----------|-------------|-----------|----------|------|-----|---|
| | W(Width) | H(Height) | D(Depth) | A | B | d |
| F1 | 85 | 170 | 124 | 67.3 | 158 | 5 |
| F2 | 97 | 194 | 133 | 85 | 184 | 5 |
| F3 | 126 | 237 | 147 | 112 | 223 | 5 |
| F4 | 168 | 298 | 160 | 154 | 283 | 6 |

NO.4 Keypad description

4. 1 Keypad appearance and keypad explanation

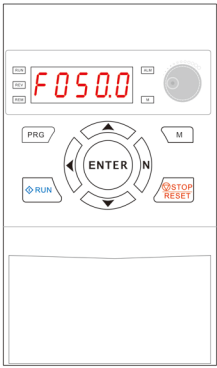


Figure 4-1 EV51 series keypad

| Item | Structure | Function description |
|------|-----------|---|
| 1 | | Display |
| 2 | | Program/exit |
| 3 | | Status display interface work as status switch key; other interface work as left shift key |
| 4 | | Reserved key |
| 5 | | RUN |
| 6 | | Potentiometer: refer to parameter P01.63 |
| 7 | | In the mode of program, work as value change key; otherwise, UP/DOWN key, refer to parameter P01.63, P02.03, P02.04 |
| 8 | | Enter |
| 9 | | Enter |
| 10 | | STOP/RESET |
| 11 | | Customization key |

4. 2 Indicator light description

| Indicator light | Status | Function description |
|-----------------|----------------------|------------------------------|
| RUN | light on/ flickering | operating /decelerating |
| REV | light on | reverse operation |
| REM | light on | remote start stop |
| ALM | light on | fault indication |
| M | light on | S1 terminal start indication |

4. 3 Display item description

| Display code | Item description |
|--------------|--------------------|
| | output frequency |
| | output current |
| | output voltage |
| | DC bus voltage |
| | Setting frequency |
| | Customized display |
| | current alarm |
| | current fault |

NO.5 Carving machine wiring diagram

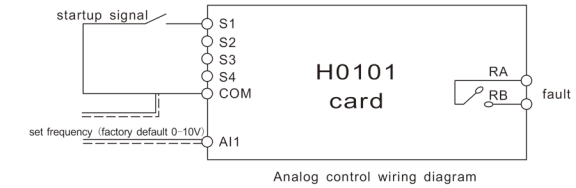
The application macro has been set for the special AC drive of EV51 series carving machine when leaving the factory. The user only needs to set the maximum frequency (P02.18), motor rated power (P06.11), rated voltage (P06.12), rated frequency P06.13), rated current (P06.14) and rated speed (P12.06) according to the motor nameplate. When leaving the factory, the motor parameters are 400Hz and 2400rpm.

Macro setting steps: stop the operation of the AC drive and restore the factory value

P01.11 = 2, set the application macro P01.20=84. Finally, set the motor and other parameters.

The speed regulation of carving machine is divided into analog speed regulation and multi-stage speed regulation. The wiring diagram and parameter table of the two control modes are as follows:

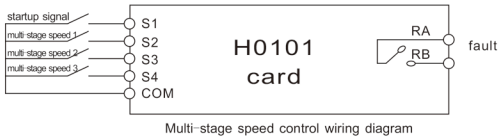
5.1 Analog control parameter table



Analog control parameter table

| Parameter No. | Function | setting value | description |
|---------------|----------------------------------|----------------------------------|--|
| P01.20 | application macro | 84 | carving machine macro |
| P02.18 | Max. Setting frequency | 400.000Hz | Max.Frequency 400.00Hz |
| P02.50 | acceleration time 0 | 5.000s | acceleration time 5S |
| P02.70 | deceleration time 0 | 5.000s | deceleration time 5S |
| P03.00 | startup command source | 3 | S1 terminal startup |
| P03.30 | Y1 terminal source(RA, RB) | 4 | fault signal output |
| P03.42 | AI1 high level voltage (current) | 9.800V(mA) | Maximum voltage/current of input signa |
| P06.11 | motor rated power | set according to motor nameplate | reference to motor nameplate |
| P06.12 | motor rated voltage | | |
| P06.13 | motor rated frequency | | |
| P06.14 | motor rated current | | |
| P12.06 | motor rated speed | | |

5. 2 Multi-stage speed control wiring diagram and parameter table



Multi-stage speed control parameter table


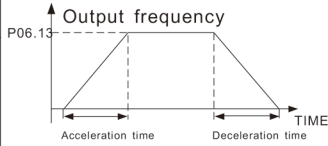
| Parameter NO. | Function | setting value | description |
|---------------|----------------------------|----------------------------------|---------------------------------------|
| P01.20 | Application macro | 84 | Carving machine macro |
| P02.18 | Max. Setting frequency | 400.000Hz | Max. Frequency 400.00Hz |
| P02.31 | Multi-stage speed 1 | 25.000% | Relative maximum frequency percentage |
| P02.32 | Multi-stage speed 2 | 37.500% | |
| P02.33 | Multi-stage speed 3 | 50.000% | |
| P02.34 | Multi-stage speed 4 | 62.500% | |
| P02.35 | Multi-stage speed 5 | 75.000% | |
| P02.36 | Multi-stage speed 6 | 87.500% | Acceleration time 5s |
| P02.37 | Multi-stage speed 7 | 100.00% | |
| P02.50 | Acceleration time 0 | 5.000s | Deceleration time 5s |
| P02.70 | Deceleration time 0 | 5.000s | Deceleration time 5s |
| P03.00 | Startup command source | 3 | S1 terminal startup |
| P03.30 | Y1 terminal source(RA, RB) | 4 | Fault signal output |
| P06.11 | Motor rated power | Set according to motor nameplate | reference to motor nameplate |
| P06.12 | Motor rated voltage | | |
| P06.13 | Motor rated frequency | | |
| P06.14 | Motor rated current | | |
| P12.06 | Motor rated speed | | |

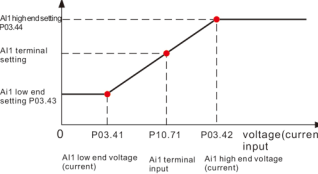
Multi stage speed comparison table

| S4 | S3 | S2 | Effective multi stage speed | Apply macro setting frequency |
|----|----|----|-----------------------------|-------------------------------|
| 0 | 0 | 1 | Multi-stage speed 1 | 100Hz |
| 0 | 1 | 0 | Multi-stage speed 2 | 150Hz |
| 0 | 1 | 1 | Multi-stage speed 3 | 200Hz |
| 1 | 0 | 0 | Multi-stage speed 4 | 250Hz |
| 1 | 0 | 1 | Multi-stage speed 5 | 300Hz |
| 1 | 1 | 0 | Multi-stage speed 6 | 350Hz |
| 1 | 1 | 1 | Multi-stage speed 7 | 400Hz |

0: means S terminal no signal
1: means S terminal has signal

NO.6 Carving machine parameter table

| Function code | Function | Description (setting range) | Factory default | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
|---------------|-------------------------------|--|-----------------------|----|----|-----------------------|---|---|---|---------------------|---|---|---|---------------------|---|---|---|---------------------|---|---|---|---------------------|---|---|---|---------------------|---|---|---|---------------------|---|---|---|---------------------|---|---|---|---------------------|------|
| P01.11 | Parameter operation | 0.Normal operation 1.Parameter initialization, initialized parameters except P1.XX 2. Initialize all parameters | 0 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| P01.41 | local address | 0~247 ⊙Function: set local address of AC drive | 1 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| P01.42 | Baud rate | 0:2400bps 1:4800bps 2:9600bps 3:19200bps 4:38400bps 5~10:reserved ⊙Function: Communication port configuration | 3 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| P01.43 | Parity check | 0.No check 1.Even parity check 2.Odd check ⊙function: Communication port configuration | 0 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| P01.44 | Data bit | 7~8 ⊙function: Communication port configuration | 8bits | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| P01.45 | Stop bit | 0.0~2.0 ⊙function: Communication port configuration | 1.0bit | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| P02.00 | Multi-stage speed source | 0~11111111 units: S1 tens: S2 hundreds' digit: S3 thousands' digit: S4 ... <table><tr><th>S4</th><th>S3</th><th>S2</th><th>Effective multi-stage</th></tr><tr><td>0</td><td>0</td><td>0</td><td>Multi-stage speed 0</td></tr><tr><td>0</td><td>0</td><td>1</td><td>Multi-stage speed 1</td></tr><tr><td>0</td><td>1</td><td>0</td><td>Multi-stage speed 2</td></tr><tr><td>0</td><td>1</td><td>1</td><td>Multi-stage speed 3</td></tr><tr><td>1</td><td>0</td><td>0</td><td>Multi-stage speed 4</td></tr><tr><td>1</td><td>0</td><td>1</td><td>Multi-stage speed 5</td></tr><tr><td>1</td><td>1</td><td>0</td><td>Multi-stage speed 6</td></tr><tr><td>1</td><td>1</td><td>1</td><td>Multi-stage speed 7</td></tr></table> *P02.00: multi-stage speed source, select corresponding external terminal, multi-stage speed 0~ 7 refer to P02.30~P02.37 *Example: select S2, S3 and S4 as effective external terminals to control multi-stage speed, P02.00 is set to 1110, and the specific 8-stage speed correspondence is shown in the table above: | S4 | S3 | S2 | Effective multi-stage | 0 | 0 | 0 | Multi-stage speed 0 | 0 | 0 | 1 | Multi-stage speed 1 | 0 | 1 | 0 | Multi-stage speed 2 | 0 | 1 | 1 | Multi-stage speed 3 | 1 | 0 | 0 | Multi-stage speed 4 | 1 | 0 | 1 | Multi-stage speed 5 | 1 | 1 | 0 | Multi-stage speed 6 | 1 | 1 | 1 | Multi-stage speed 7 | 1110 |
| S4 | S3 | S2 | Effective multi-stage | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 0 | 0 | 0 | Multi-stage speed 0 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 0 | 0 | 1 | Multi-stage speed 1 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 0 | 1 | 0 | Multi-stage speed 2 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 0 | 1 | 1 | Multi-stage speed 3 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 1 | 0 | 0 | Multi-stage speed 4 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 1 | 0 | 1 | Multi-stage speed 5 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 1 | 1 | 0 | Multi-stage speed 6 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 1 | 1 | 1 | Multi-stage speed 7 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| P02.10 | Setting (frequency) source F1 | 0:key board  key board setting source: P01.63 1: multi-stage speed 0:key board digital set 2:A11 1:key board potentiometer set 3:A12 5:communication | 1 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| P02.18 | Max. Setting value | 0.000~99999.000 * Principle explanation: limit the range of setting value. When each setting source is in%, the maximum setting value (P02.18) represents 100%, means the maximum setting value is taken as the benchmark. | 400.000Hz | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| P02.24 | Jog frequency | - 1000.000%~1000.000% Function: set jog frequency, jog command refers to P03.03 | 10.000% | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| P02.30 | Multi-stage speed 0 | - 1000.000%~1000.000% Function: multi-stage setting, relative P02.18 Maximum set percentage | 0.000% | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| P02.31 | Multi-stage speed 1 | | 25.000% | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| P02.32 | Multi-stage speed 2 | | 37.500% | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| P02.33 | Multi-stage speed 3 | | 50.000% | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| P02.34 | Multi-stage speed 4 | | 62.500% | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| P02.35 | Multi-stage speed 5 | | 75.000% | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| P02.36 | Multi-stage speed 6 | | 87.500% | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| P02.37 | Multi-stage speed 7 | | 100.00% | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| P02.50 | Acceleration time | 0.050s~3600.000s * Principle explanation: As shown in the figure, the acceleration time refers to the acceleration from 0Hz to P06.13 time required for rated frequency of motor  | 5.000s | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| P02.70 | Deceleration time | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |

| Function code | Function | Description (setting range) | Factory default | | | | | | | | | | | | | | | | | | |
|---------------|---|--|-----------------|-----|---------------|-----------|-----------|----|----|---|----|-----|-----|-----|-----|---------------|-----------|-----------|----|----|---|
| P03.00 | Startup command source | 0: no effect 1: key board 2: communication 3:S1 4:S2 5:S3 6:S4 ... | 3 | | | | | | | | | | | | | | | | | | |
| P03.01 | Reverse startup command source | | 0 | | | | | | | | | | | | | | | | | | |
| P03.02 | Reverse command source | Function: select the command source (when the corresponding command source is the key board, the reverse command, jog command and free parking command all come from the key board custom key M) | 0 | | | | | | | | | | | | | | | | | | |
| P03.03 | Jog command source | | 1 | | | | | | | | | | | | | | | | | | |
| P03.04 | Stop command source | * Reverse startup command: the setting value is reversed and the start command is issued. * Reverse command: the setting value is reversed. * Jog command: jog function. The priority is higher than the start command and lower than the stop command. | 0 | | | | | | | | | | | | | | | | | | |
| P03.05 | Free parking command source | <table><tr><td>16</td><td>15</td><td>14</td><td>13</td><td>12</td><td>11</td><td>10</td><td>9</td><td>8</td></tr><tr><td>S14</td><td>S13</td><td>S12</td><td>S11</td><td>S10</td><td>S9</td><td>S8</td><td>S7</td><td>S6</td></tr></table> | 16 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | S14 | S13 | S12 | S11 | S10 | S9 | S8 | S7 | S6 | 0 |
| 16 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | | | | | | | | | | | | | |
| S14 | S13 | S12 | S11 | S10 | S9 | S8 | S7 | S6 | | | | | | | | | | | | | |
| P03.06 | Free parking command source | <table><tr><td>7</td><td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td><td>0</td></tr><tr><td>S5</td><td>S4</td><td>S3</td><td>S2</td><td>S1</td><td>Communication</td><td>Key board</td><td>No effect</td></tr></table> | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | S5 | S4 | S3 | S2 | S1 | Communication | Key board | No effect | 1 | | |
| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | | | | | | | | | | | | | | |
| S5 | S4 | S3 | S2 | S1 | Communication | Key board | No effect | | | | | | | | | | | | | | |
| P03.30 | Y1 terminal source (RA, RB or RA1, RB1) | 0: always 0 1: always 1 2: stopped already 3: running 4: fault 5: alarm 6: reversing 7: ready 1350: running at 0 speed 1351: frequency arrived Note: Only when setting carving machine application macro, 1350 and 1351 are valid. | 4 | | | | | | | | | | | | | | | | | | |
| P03.32 | Y2 terminal source (RA2, RB2) | | 1351 | | | | | | | | | | | | | | | | | | |
| P03.34 | Y3 terminal source (RA3, RB3, RC3) | | 1350 | | | | | | | | | | | | | | | | | | |
| P03.41 | A11 low end voltage (current) | - 999999.000~999999.000 ⊙function: analog input A11 setting *A11 low end voltage(current): set minimum voltage(current) of input signal. | 0.200V(mA) | | | | | | | | | | | | | | | | | | |
| P03.42 | A11 high end voltage (current) | *A11 high end voltage(current): set Max. Voltage (current) of input signal. *A11 low end setting: set the corresponding value of low-end voltage. *A11 high end setting: set the corresponding value of high-end voltage. | 9.800V(mA) | | | | | | | | | | | | | | | | | | |
| P03.43 | A11 low end setting | Range setting  | 0.000% | | | | | | | | | | | | | | | | | | |
| P03.44 | A11 high end setting | | 100.00% | | | | | | | | | | | | | | | | | | |
| P05.00 | Control mode | 0:VF 1:vector control function: Select motor control algorithm | 1 | | | | | | | | | | | | | | | | | | |
| P05.20 | Stop function | units: 0: free parking;1: DC braking Tens: 1. Precise parking * Principle explanation: During the stop process, when the output frequency is less than the stop frequency, the stop function starts to work. Precise parking: when parking at any speed, the number of motor turns is the same, so as to realize the one-to-one repeatability of parking position. To achieve the best results, the deceleration time shall be extended as far as possible without triggering the over voltage and over current stall prevention function. | 1 | | | | | | | | | | | | | | | | | | |
| P05.21 | Stop frequency | 0.000Hz~1000.000Hz The explanation refers to P05.20 | 10.000Hz | | | | | | | | | | | | | | | | | | |
| P05.22 | DC braking current | 0.000%~300.000% Set the current of DC braking | 100.000% | | | | | | | | | | | | | | | | | | |
| P05.23 | DC braking time | 0.000s~1000.000s When it is set to 1000.000, keep braking until the free stop or startup signal is received. | 1.000s | | | | | | | | | | | | | | | | | | |
| P06.05 | Carry frequency | 2kHz~16kHz ⊙Function: Set carry frequency | *kHz | | | | | | | | | | | | | | | | | | |
| P06.11 | Motor rated power | 0.000kW~100000.000kW ⊙Function: Set motor rated parameter | *kW | | | | | | | | | | | | | | | | | | |
| P06.12 | Motor rated voltage | 0V~1000V ⊙Function: Set motor rated parameter | *V | | | | | | | | | | | | | | | | | | |
| P06.13 | Motor rated frequency | 1Hz~3000Hz ⊙Function: Set motor rated parameter | 400Hz | | | | | | | | | | | | | | | | | | |
| P06.14 | Motor rated current | 0.00A~1000.00A ⊙Function: Set motor rated parameter | *A | | | | | | | | | | | | | | | | | | |
| P10.61 | Current fault | - | 0 | | | | | | | | | | | | | | | | | | |
| P10.62 | Previous fault | - | 0 | | | | | | | | | | | | | | | | | | |
| P10.63 | The first two faults | - | 0 | | | | | | | | | | | | | | | | | | |

| Function code | Function | Description (setting range) | Factory default |
|---------------|---|--|-----------------|
| P11.10 | Output frequency of current fault | -- | 0.0Hz |
| P11.11 | Output current of current fault | -- | 0.00A |
| P11.12 | Bus voltage of current fault | -- | 0.0V |
| P11.13 | AC drive temperature of current fault | -- | 0℃ |
| P11.14 | S terminal status of current fault | -- | 0 |
| P11.15 | Y terminal status of current fault | -- | 0 |
| P11.16 | Cumulative power on time of current fault | -- | 0.000h |
| P12.06 | Motor rated speed | 10rpm~65535rpm ⊙Function: Set motor parameter | 24000rpm |

NO.7 Fault code

| Fault Code | Protection function | Description |
|------------|-------------------------|--|
| E0001 | system abnormality | AC drive hardware failure or software failure |
| E0004 | ground fault | Abnormal resistance to ground, cause electric leakage |
| E0005 | short circuit to ground | short circuit to ground |
| E0006 | output short circuit | inverter cut off output when inverter output current is 250% larger than inverter rated current. |
| E0007 | output over current | inverter cut off output when inverter output current is 200% larger than inverter rated current. |
| E0008 | DC bus over voltage | inverter cut off output if main circuit DC voltage is higher than 400V(220V motor type) or 800V(380V motor type) when motor decelerates. |
| E0009 | DC bus low voltage | input voltage decrease, inverter cut off output if main circuit DC voltage too low. |
| E0010 | inverter over heat | inverter cut off output if cooling fin is over heat. |
| E0011 | self-learning failure | self-learning parameter wrong or motor abnormal. |
| E0013 | rectifier over heat | rectifier module over heat. |
| E0014 | U phase loss | output U phase loss. |
| E0015 | V phase loss | output V phase loss. |
| E0016 | W phase loss | output W phase loss. |
| E0019 | no motor connect | motor lost connection during operation. |
| E0020 | input phase loss | power input phase loss. |
| E0021 | inverter over load | inverter cut off output when inverter output current ex (120%) 60S |
| E0022 | over torque | motor over torque |
| E0024 | motor over heat | motor temperature is over heat. |
| E0025 | motor over load | inverter cut off output when inverter output current ex (120%) 60S |
| E0026 | current limit | output current exceed setting limit threshold. |
| E0027 | Input power down | The input voltage is lower than the power down standard value (P05.86) |
| E0033 | ST0 | Safe torque output stop function operation |
| E0034 | ST1 | Alarm of ST1 internal circuit diagnosis |
| E0035 | ST2 | Alarm of ST2 internal circuit diagnosis |
| E0036 | ST3 | Alarm of internal circuit diagnosis |
| E0063 | user fault | user defined fault(P03.08) |

Note: The alarm code is compared to the above table, for example: the keyboard displays "A0025" which means the motor overload alarm.